ASSP For Power Management Applications

Switching Regulator Controller (Switchable between push-pull and single-end functions)

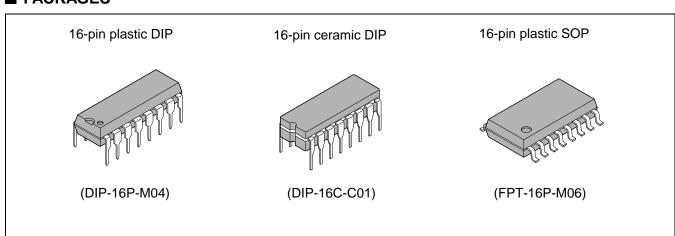
MB3759

DESCRIPTION

The MB3759 is a control IC for constant-frequency pulse width modulated switching regulators. The IC contains most of the functions required for switching regulator control circuits. This reduces both the component count and assembly work.

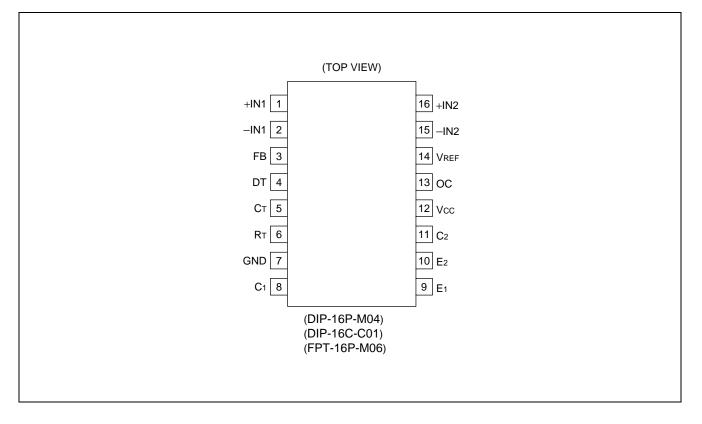
FEATURES

- Drives a 200 mA load
- Can be set to push-pull or single-end operation
- Prevents double pulses
- · Adjustable dead-time
- Error amplifier has wide common phase input range
- Built in a circuit to prevent misoperation due to low power supply voltage.
- Built in an internal 5 V reference voltage with superior voltage reduction characteristics

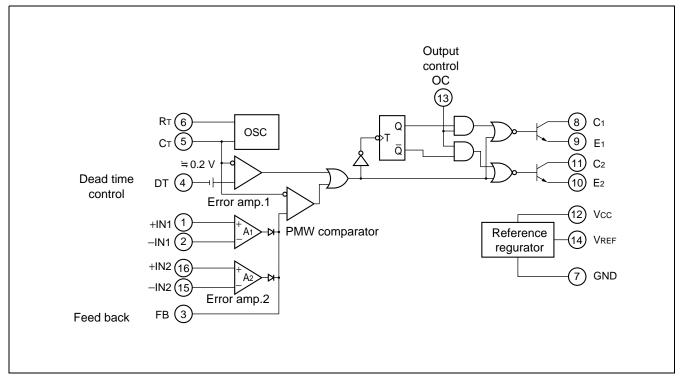


PACKAGES

■ PIN ASSIGNMENT



BLOCK DIAGRAM



ABSOLUTE MAXIMUM RATINGS

Parameter		Symbol	Condition	Ra	Unit	
		Symbol	Condition	Min	Min Max	
Power supply voltage		Vcc	—	—	41	V
Collector output voltage		Vce	_		41	V
Collector output current		ICE	_		250	mA
Amplifier input voltage		Vi	—		Vcc + 0.3	V
	Plastic DIP		Ta ≤ +25 °C		1000	
Power dissipation	Ceramic DIP	PD	Ta ≤ +60 °C		800	mW
	SOP *		Ta ≤ +25 °C		620	
Operating temperature		Тор	_	-30	+85	°C
Storage temperature		Tstg	—	-55	+125	°C

*: When mounted on a 4 cm square double-sided epoxy circuit board (1.5 mm thickness) The ceramic circuit board is 3 cm x 4 cm (0.5 mm thickness)

■ RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Value				
Falameter	Symbol	Min	Тур	Max	Unit	
Power supply voltage	Vcc	7	15	32	V	
Collector output voltage	Vce	—	_	40	V	
Collector output current	ICE	5	_	200	mA	
Amplifier input voltage	Vin	-0.3	0 to V _R	Vcc – 2	V	
FB sink current	Isink	—	_	0.3	mA	
FB source current	ISOURCE	—	_	2	mA	
Reference section output current	REF	_	5	10	mA	
Timing resistor	R⊤	1.8	30	500	kΩ	
Timing capacitor	С⊤	470	1000	10 ⁶	pF	
Oscillator frequency	fosc	1	40	300	kHz	
Operating temperature	Тор	-30	+25	+85	°C	

Note: Values are for standard derating conditions. Give consideration to the ambient temperature and power consumption if using a high supply voltage.

WARNING: The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges.

Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure.

No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their FUJITSU representatives beforehand.

WARNING: Semiconductor devices can be permanently damaged by application of stress (voltage, current, temperature, etc.) in excess of absolute maximum ratings. Do not exceed these ratings.

■ ELECTRICAL CHARACTERISTICS

(Vcc = 15 V, Ta = +25 °C)

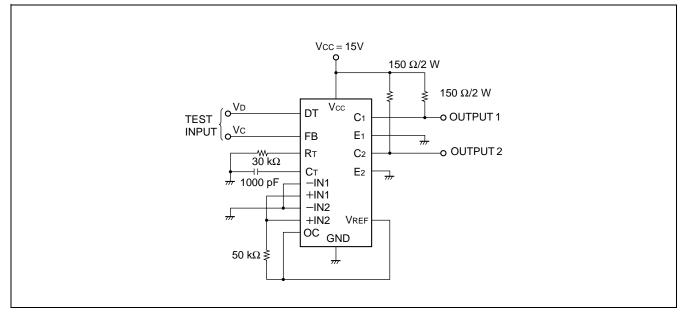
					(vcc = 15 v, 1a			= 123 0)
Parameter		Symbol Condition	Value			Unit		
			Condition	Min	Тур	Max	Onit	
Output voltage		Vref	lo = 1 mA	4.75	5.0	5.25	V	
	Input regulation		$\Delta V_{R(IN)}$	$7 V \le V_{CC} \le 40 V$, Ta = +25 °C	_	2	25	mV
	Load regulation		$\Delta V_{\text{R(LD)}}$	$1 \text{ mA} \le I_0 \le 10 \text{ mA},$ Ta = +25 °C		-1	-15	mV
Reference section	Temperature	e stability	$\Delta V_{R}/\Delta T$	–20 °C ≤ Ta ≤ + 85 °C	_	±200	±750	μV/°C
	Short circuit output current		lsc	_	15	40	_	mA
	Reference lockout voltage		_	_	_	4.3	_	V
	Reference hysteresis voltage		_	_	_	0.3	_	V
	Oscillator frequency Standard deviation of frequency Section Frequency change with voltage		fosc	Rτ = 30 kΩ, Cτ = 1000 pF	36	40	44	kHz
				Rτ = 30 kΩ, Cτ = 1000 pF	_	±3	_	%
section			_	7 V ≤ V _{cc} ≤ 40 V, Ta = +25 °C	_	±0.1	_	%
	Frequency change with temperature		∆fosc/∆T	–20 °C ≤ Ta ≤ +85 °C	_	±0.01	±0.03	%/°C
Input bias current		urrent	lo	$0 \leq V_l \leq 5.25 \ V$	_	-2	-10	μA
Dead-time control section	Maximum duty cycle (Each output)			V1 = 0	40	45	_	%
	Input threshold	0% duty cycle	Vdo	_	_	3.0	3.3	V
	voltage Max	Max. duty cycle	Vdm		0	—		V

(Continued)

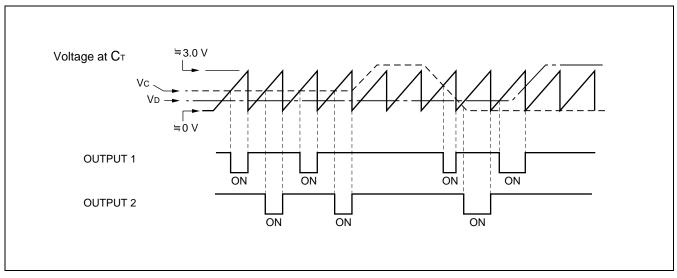
(Vcc = 15 V, Ta = +25 °C)

	Parameter				(Vcc = 15 V, Ta = Value			
			Symbol Condition	Min	Тур	Max	Unit	
	Input offset	voltage	Vio	Vo (pin3) = 2.5 V	_	±2	±10	mV
	Input offset current		lio	Vo (pin3) = 2.5 V	_	±25	±250	nA
	Input bias c	urrent	lı lı	Vo (pin3) = 2.5 V	_	-0.2	-1.0	μΑ
	Common-mode input voltage		Vсм	$7 \text{ V} \leq \text{V}_{CC} \leq 40 \text{ V}$	-0.3	_	Vcc – 2	V
Error amplifier	Open-loop v amplificatio		Av	$0.5 V \le V_0 \le 3.5 V$	70	95		dB
section	Unity-gain b	andwidth	BW	A∨ = 1	—	800	—	kHz
	Common-m rejection rat		CMR	Vcc = 40 V	65	80		dB
	Output sink current	ISINK	Isink	$-5 V \le V_{ID} \le -15 mV$, Vo = 0.7 V	0.3	0.7		mA
	(pin 3)	ISOURCE	ISOURCE	$\begin{array}{l} 15 \text{ mV} \leq \text{V}_{\text{ID}} \leq 5\text{V}, \\ \text{V}_{\text{O}} = 3.5 \text{ V} \end{array}$	-2	-10		mA
	Collector lea	akage current	Ico	Vce = 40 V, Vcc = 40 V		_	100	μΑ
	Emitter leak	age current	leo			_	-100	μΑ
Output section		Emitter grounded	VSAT(C)	Ve = 0, Ic = 200 mA		1.1	1.3	V
saturation voltage	Emitter follower	VSAT(E)	Vc = 15 V, I _E = -200 mA	—	1.5	2.5	V	
	Output contr current	rol input	Горс	VI = VREF	—	1.3	3.5	mA
PWM	Input thresh	old voltage	Vтн	0% Duty		4	4.5	V
comparator section	Input sink cu	urrent (pin 3)	Isink	Vo (pin3) = 0.7 V	0.3	0.7	—	mA
Power supply current		Icc	V(pin4) = 2 V, See Fig-2	_	8	_	mA	
Standby current		Ιςςα	V(pin6) = VREF, I/O open		7	12	mA	
	Rise time	time Emitter	tR	RL = 68 Ω	_	100	200	ns
Switching	Fall time grounded	grounded	t⊧	RL = 68 Ω	_	25	100	ns
characteristics	Rise time	Emitter	tR	RL = 68 Ω	_	100	200	ns
	Fall time follower	t⊧	R∟ = 68 Ω	_	40	100	ns	

■ TEST CIRCUIT



OPERATING TIMING





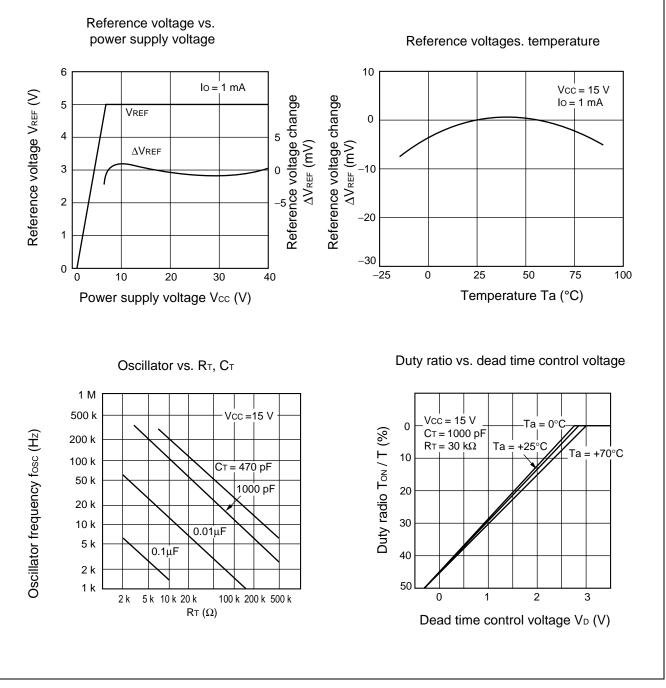
■ OSCILLATION FREQUENCY

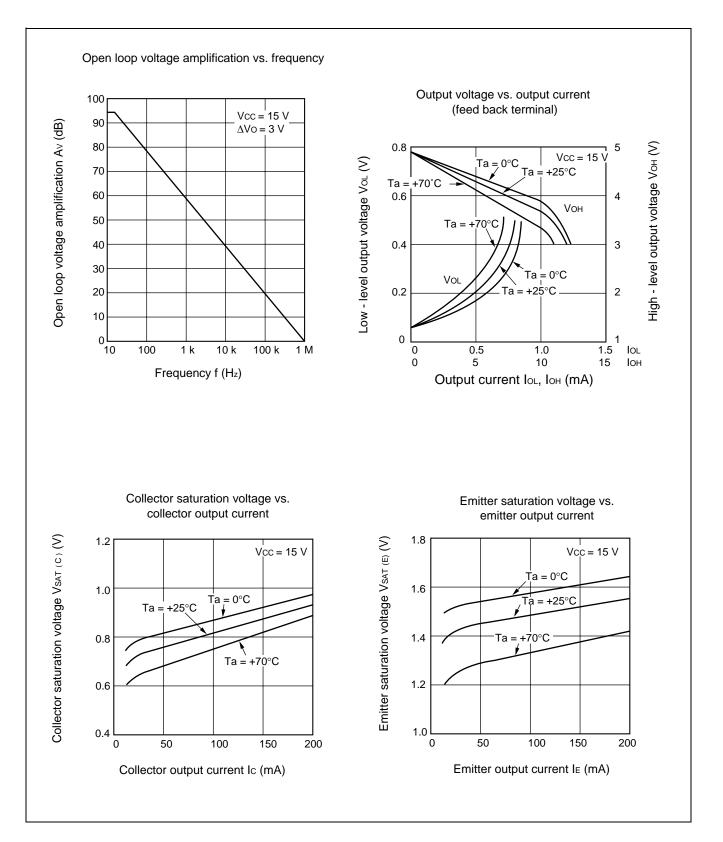
Rτ : kΩ Cτ : μF fosc : kHz

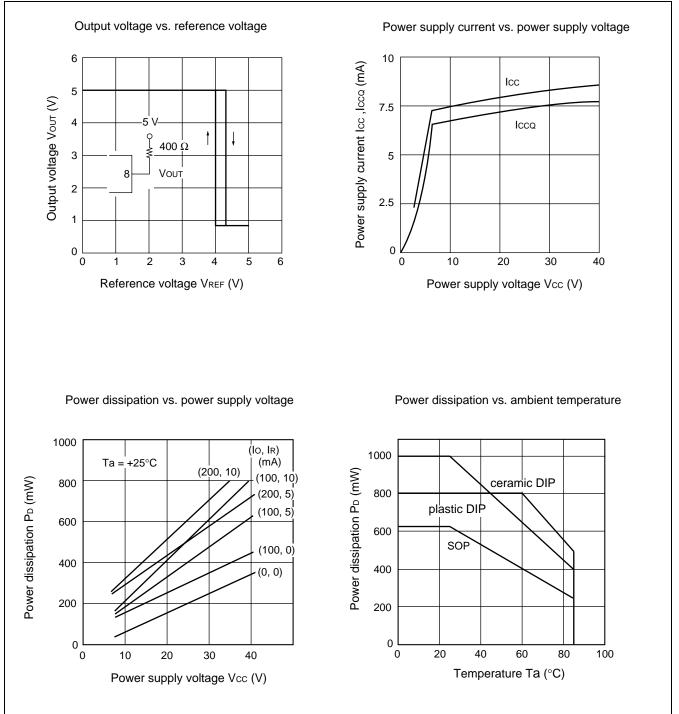
■ OUTPUT LOGIC TABLE

Input (Output Control)	Output State	
GND	Single-ended or parallel output	
Vref	Push-pull	

■ TYPICAL CHARACTERISTICS







BASIC OPERATION

Switching regulators can achieve a high level of efficiency. This section describes the basic principles of operation using a chopper regulator as an example.

As shown in the diagram, diode D provides a current path for the current through inductance L when Q is off. Transistor Q performs switching and is operated at a frequency that provides a stable output. As the switching element is saturated when Q is on and cutoff when Q is off, the losses in the switching element are much less than for a series regulator in which the pass transistor is always in the active state.

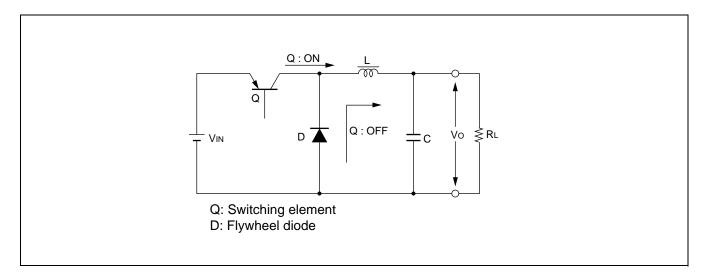
While Q is conducting, the input voltage V_{IN} is supplied to the LC circuit and when Q is off, the energy stored in L is supplied to the load via diode D. The LC circuit smooths the input to supply the output voltage.

The output voltage Vo is given by the following equation.

Ton

$$V_0 = \frac{1000}{\text{Ton} + \text{Toff}} V_{\text{IN}} = \frac{1000}{\text{T}} V_{\text{IN}}$$

Ton



As indicated by the equation, variation in the input voltage is compensated for by controlling the duty cycle (Ton/T). If V_{IN} drops, the control circuit operates to increase the duty cycle so as to keep the output voltage constant. The current through L flows from the input to the output when Q is on and through D when Q is off. Accordingly, the average input current I_{IN} is the product of the output current and the duty cycle for Q.

$$IIN = \frac{Ton}{T} Io$$

The theoretical conversion efficiency if the switching loss in Q and loss in D are ignored is as follows.

$$\begin{split} \eta &= \frac{P_O}{P_{IN}} \times 100 \ (\%) \\ &= \frac{V_O \cdot I_O}{V_{IN} \cdot I_{IN}} \times 100 \\ &= \frac{V_{IN} \cdot I_O \cdot T_{ON} / T}{V_{IN} \cdot I_O \cdot T_{ON} / T} \times 100 \\ &= 100 \ (\%) \end{split}$$

The theoretical conversion efficiency is 100%. In practice, losses occur in the switching element and elsewhere, and design decisions to minimize these losses include making the switching frequency as low as practical and setting an optimum ratio of input to output voltage.

SWITCHING ELEMENT

1. Selection of the Switching Transistor

It can be said that the success or otherwise of a switching regulator is determined by the choice of switching transistor. Typically, the following parameters are considered in selecting a transistor.

- Withstand voltage
- Current
- Power
- Speed

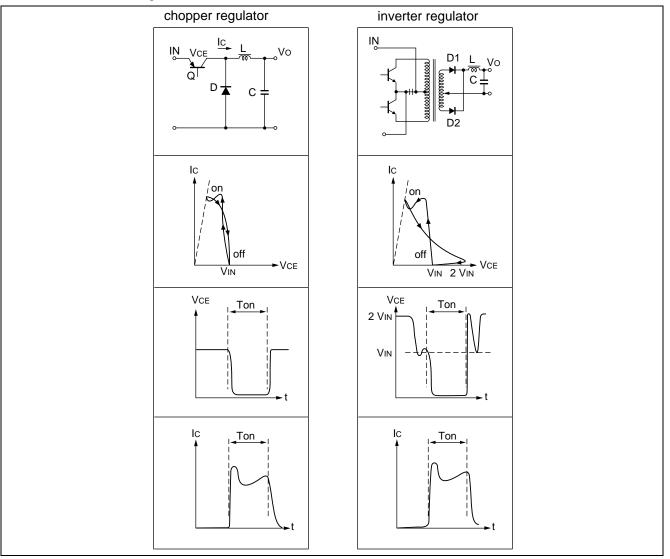
For the withstand voltage, current, and power, it is necessary to determine that the area of safe operation (ASO) of the intended transistor covers the intended range for these parameters.

The speed (switching speed: rise time tr, storage time tstg, and fall time tf) is related to the efficiency and also influences the power.

The figures show the transistor load curve and VCE - Ic waveforms for chopper and inverter-type regulators.

The chopper regulator is a relatively easy circuit to deal with as the diode clamps the collector. A peak can be seen immediately after turn-on. However, this is due to the diode and is explained later.

In an inverter regulator, the diodes on the secondary side act as a clamp. Viewed from the primary side, however, a leakage inductance is present. This results in an inductive spike which must be taken account of as it is added to double the V_{IN} voltage.

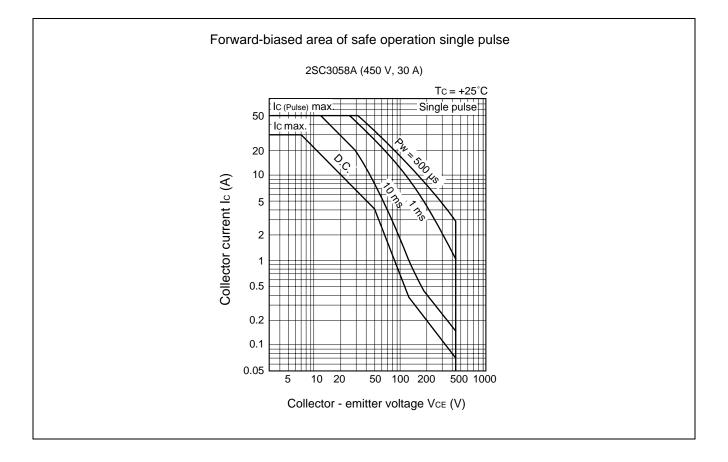


The figure below shows an example of the ASO characteristics for a forward-biased power transistor (2SC3058A) suitable for switching.

Check that the ASO characteristics for the transistor you intend to use fully covers the load curve. Next, check whether the following conditions are satisfied. If so, the transistor can be expected to perform the switching operation safely.

- The intended ON time does not exceed the ON-time specified for the ASO characteristic.
- The OFF-time ASO characteristic satisfies the intended operation conditions.
- Derating for the junction temperature has been taken into account.

For a switching transistor, the junction temperature is closely related to the switching speed. This is because the switching speed becomes slower as the temperature increases and this affects the switching losses.



2. Selecting the Diode

Consideration must be given to the switching speed when selecting the diode. For chopper regulators in particular, the diode affects the efficiency and noise characteristics and has a big influence on the performance of the switching regulator.

If the reverse recovery time of the diode is slower than the turn-on time of the transistor, an in-rush current of more than twice the load current occurs resulting in noise (spikes) and reduced efficiency.

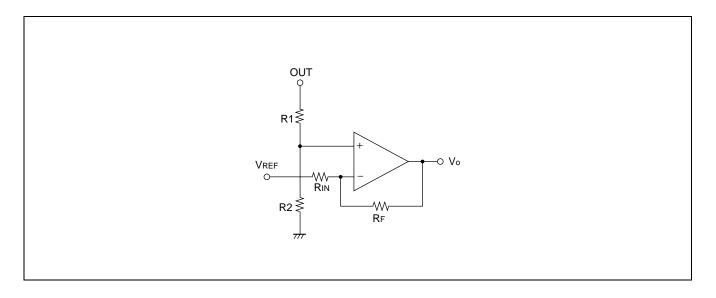
As a rule for diode selection, use a diode with a reverse recovery time t_{rr} that is sufficiently faster than the transistor t_{r} .

■ APPLICATION IN PRACTICAL CIRCUITS

1. Error Amplifier Gain Adjustment

Take care that the bias current does not become large when connecting an external circuit to the FB pin (pin 3) for adjusting the amplifier gain. As the FB pin is biased to the low level by a sink current, the duty cycle of the output signal will be affected if the current from the external circuit is greater than the amplifier can sink. The figure below shows a suitable circuit for adjusting the gain.

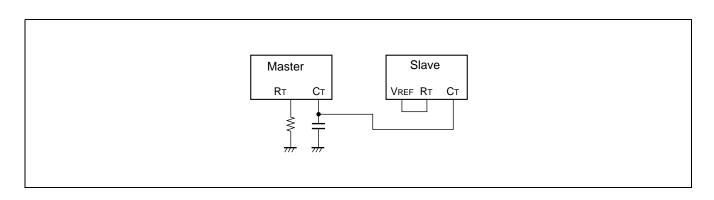
It is very important that you avoid having a capacitive load connected to the output stage as this will affect the response time.



2. Synchronized Oscillator Operation

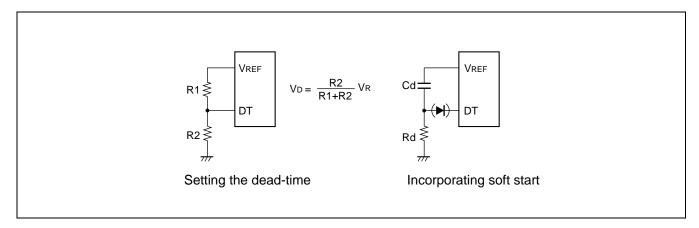
The oscillator can be halted by connecting the C_T pin to the GND pin. If supplying the signal externally, halt the internal oscillator and input to the C_T pin.

Using this method, multiple ICs can be used together in synchronized operation. For synchronized operation, set one IC as the master and connect the other ICs as shown in the diagram.

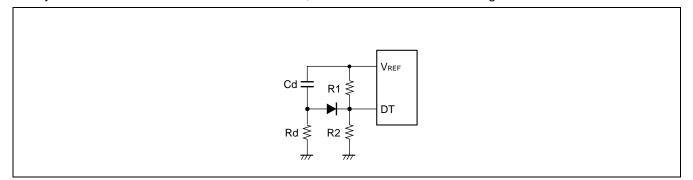


3. Soft Start

A soft start function can be incorporated by using the dead-time control element.

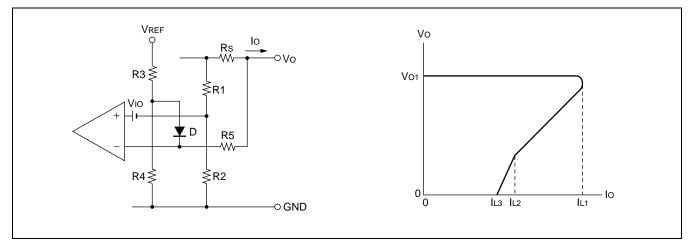


When the power is turned on, Cd is not yet charged and the DT input is pulled to the V_{REF} pin causing the output transistor to turn off. Next, the input voltage to the DT pin drops in accordance with the Cd, Rd constant causing the output pulse width to increase steadily, providing stable control circuit operation. If you wish to use both dead-time and softstart, combine these in an OR configuration.



4. Output Current Limiting (Fallback system using a detection resistor inserted on the output side)

(1) Typical example



• Initial limit current IL1

$$Vo > \frac{R4}{R3 + R4} VREF$$
 The condition for V_0 is:

As the diode is reverse biased

Rs IL1 =
$$\frac{R1}{R1 + R2}$$
 Vo – Vio
∴IL1 = $\frac{R1}{R1 + R2} \frac{Vo}{Rs} - \frac{Vio}{Rs}$ Eq. (1) (where R2 >> R1)

 V_{IO} is the input offset voltage to the op-amp (-10 mV $\leq V_{IO} \leq$ +10 mV) and this causes the variation in I_L. Accordingly, if for example the variation in I_L is to be limited to ±10 %, using equation (1) and only considering the variation in the offset voltage gives the following:

IO =
$$\frac{1}{Rs} \frac{R1}{R1 + R2} (VO + VEE) - \frac{VIO}{Rs} (R2 >> R1)$$

This indicates a setting of 100 mV or more is required.

• Polarity change point IL2

As this is the point where the diode becomes forward biased, it can be calculated by substituting [R4/(R3+R4) $V_{REF} - V_D$] for V₀ in equation (where V_D is the forward voltage of the diode).

$$I_{L2} = \frac{R1}{R1 + R2} \frac{R4/(R3 + R4) \cdot V_{REF} - V_D}{Rs} - \frac{V_{IO}}{Rs}$$

• Final limit current IL3

The limit current for $V_0 = 0$ when R2 >> R1 is the point where the voltages on either side of Rs and on either side of R5 are biased.

Rs IL3 =
$$\frac{R4R5 VREF - R3R5 VD - R4R5 VD}{R3R4 + R3R5 + R4R5}$$
 - VIO
∴IL3 = $\frac{1}{Rs} \frac{1}{1 + (R_3 // R_4) / R_5} (\frac{R4}{R3 + R4} VREF - VD) - \frac{VIO}{Rs}$ (2) Eq.

R3//R4 is the resistance formed by R3 and R4 in parallel (R3R4/(R3 + R4)). When R3//R4 << R5, equation (2) becomes:

$$I_{L3 C} = \frac{1}{Rs} \left(\frac{R4}{R3 + R4} V_{REF} - V_D \right) - \frac{V_{IO}}{Rs}$$

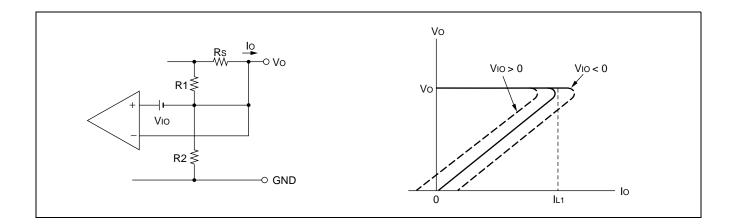
In addition to determining the limit current I_{L3} for $V_0 = 0$, R3, R4, R5, and diode D also operate as a starter when the power is turned on.

Starter circuit

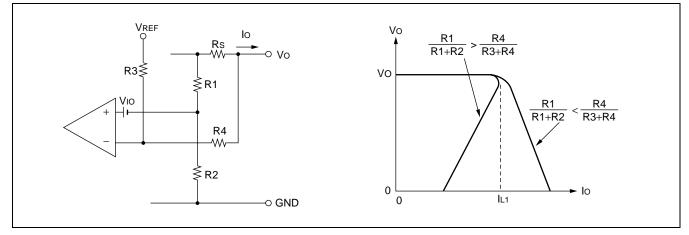
The figure below shows the case when the starter circuit formed by R3, R4, R5, and D is not present. The output current lo after the operation of the current limiting circuit is:

$$IO = \frac{R1}{R1 + R2} \frac{VO}{Rs} - \frac{VO}{Rs}$$

When $V_0 = 0$ such as when the power is turned on, the output current $I_0 = -V_{10} / R_s$ and, if the offset voltage V_{10} is positive, the output current is limited to being negative and therefore the output voltage does not rise. Accordingly, if using a fallback system with a detection resistor inserted in the output, always include a starter circuit, expect in the cases described later.



(2) Example that does not use a diode

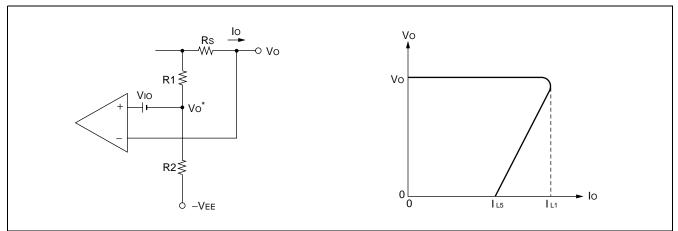


The output current lo after current limiting is:

$$IO = \frac{1}{RS} \left[\left(\frac{R1}{R1 + R2} - \frac{R4}{R3 + R4} \right) VO + \frac{R4}{R3 + R4} VREF - VIO \right] (R2 >> R1)$$

In this case, a current flows into the reference voltage source via R3 and R4 if $V_0 > V_{REF}$. To maintain the stability of the reference voltage, design the circuit such that this does not exceed 200 μ A.

(3) When an external stabilized negative power supply is present



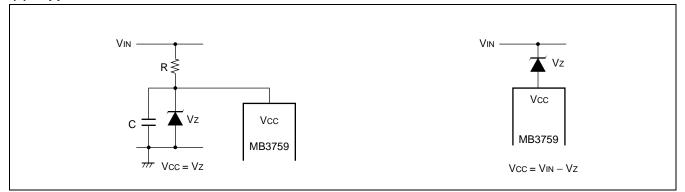
The output current lo after current limiting is:

$$IO = \frac{1}{RS} \frac{R1}{R1 + R2} (VO + VEE) - \frac{VIO}{RS} (R2 >>R1)$$

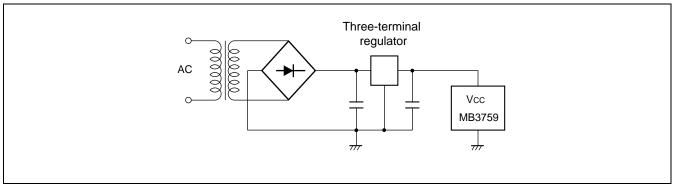
If the output is momentarily shorted, Vo^* goes briefly negative. In this case, set the voltage across R1 to 300 mV or less to ensure that a voltage of less than -0.3 V is not applied to the op-amp input.

5. Example Power Supply Voltage Supply Circuit

(1) Supplied via a Zener diode



(2) Supplied via a three-terminal regulator

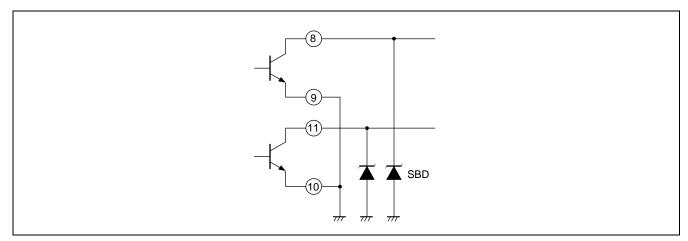


6. Example Protection Circuit for Output Transistor

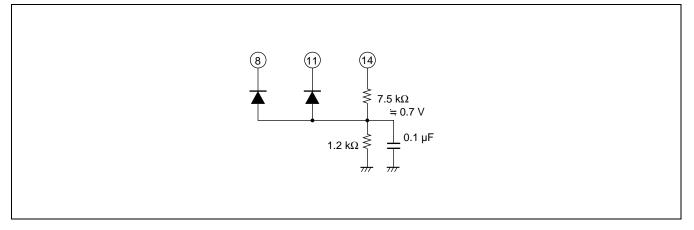
Due to its monolithic IC characteristics, applying a negative voltage greater than the diode voltage (\pm 0.5 V) to the substrate (pin 7) of the MB3759 causes a parasitic effect in the IC which can result in misoperation.

Accordingly, the following measures are required if driving a transformer or similar directly from the output transistor of the IC.

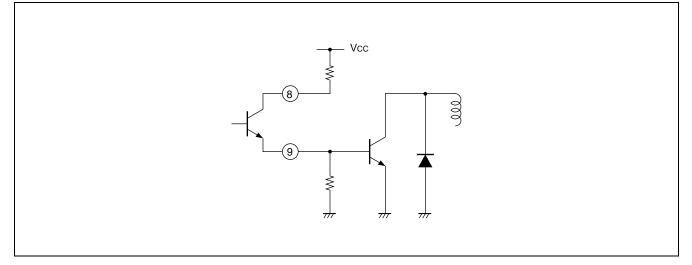
(1) Protect the output transistor from the parasitic effect by using a Schottky barrier diode.



(2) Provide a bias at the anode-side of the diode to clamp the low level side of the transistor.

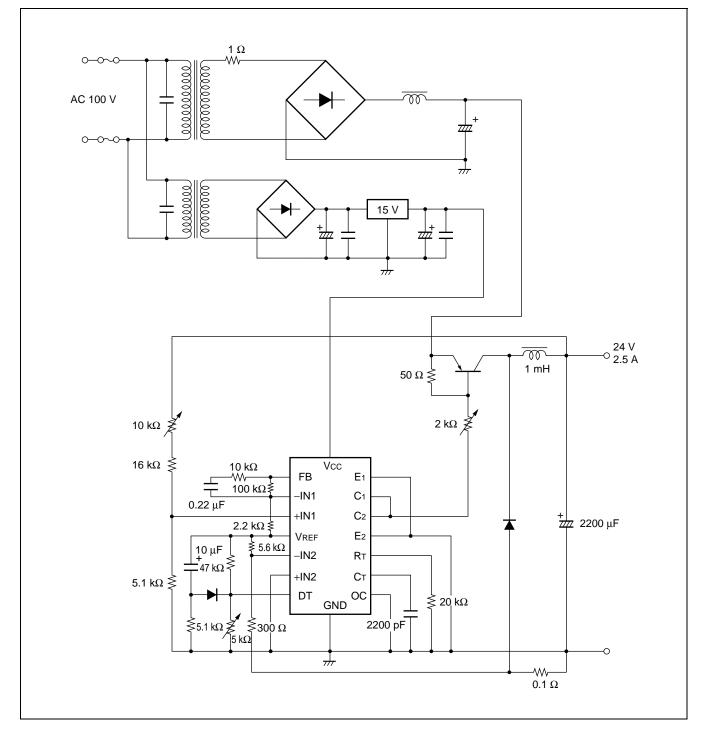


(3) Drive the transformer via a buffer transistor.



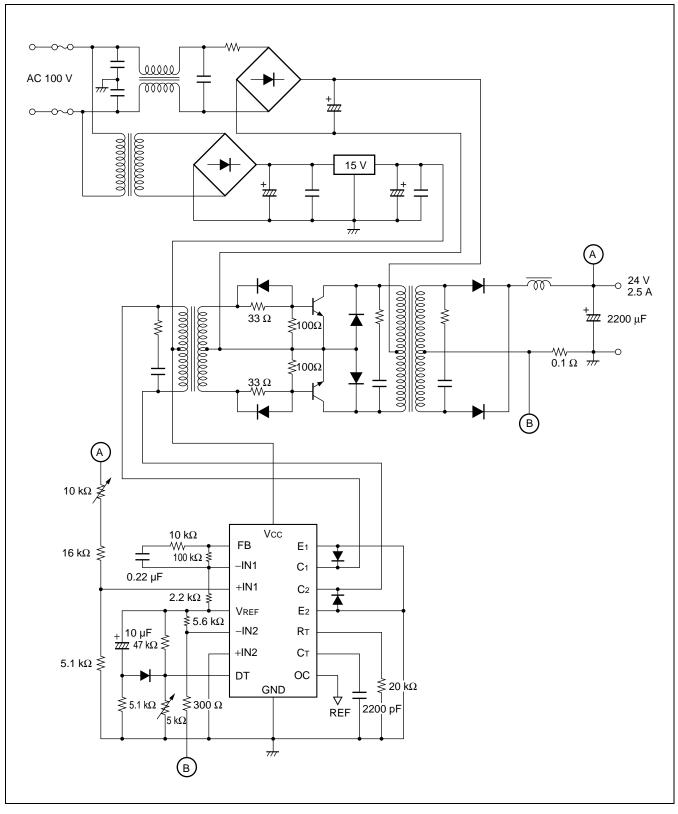
7. Typical Application

(1)Chopper regulator



21

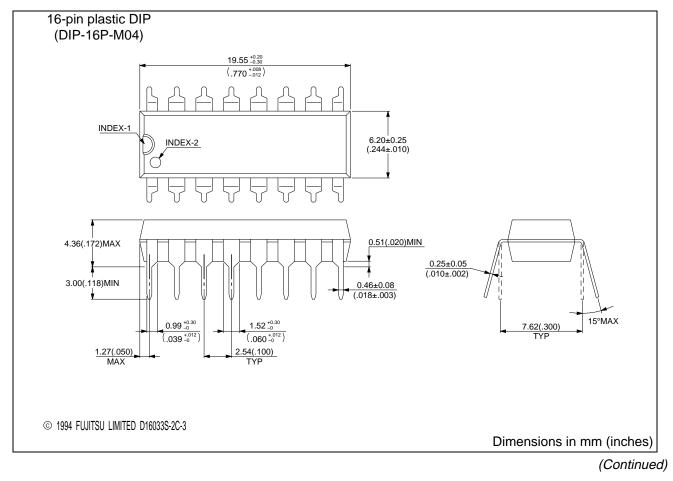
(2) Inverter regulator

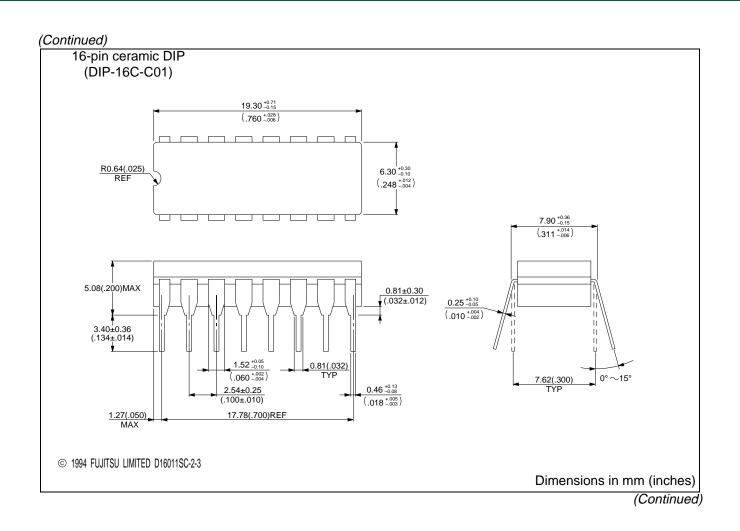


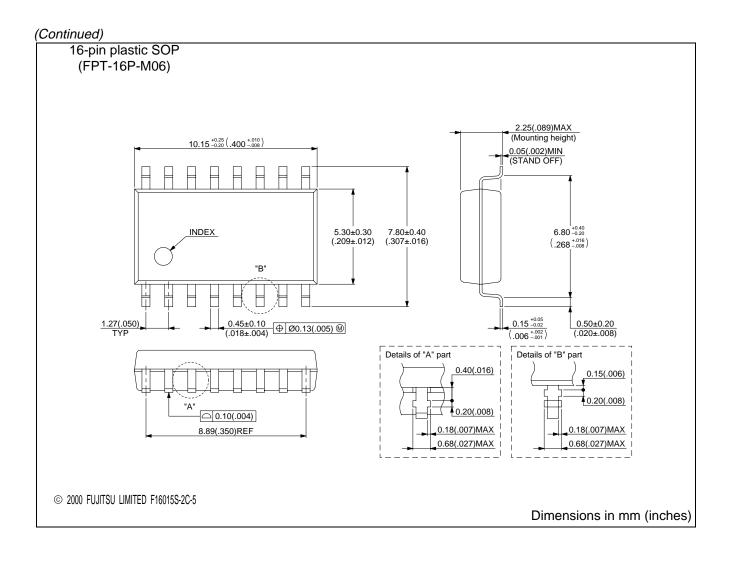
■ ORDERING INFORMATION

Part number	Package	Remarks
MB3759P	16-pin plastic DIP (DIP-16P-M04)	
MB3759C	16-pin ceramic DIP (DIP-16C-C01)	
MB3759PF	16-pin plastic SOP (FPT-16P-M06)	

■ PACKAGE DIMENSIONS







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Any semiconductor devices have inherently a certain rate of failure. You must protect against injury, damage or loss from such failures by incorporating safety design measures into your facility and equipment such as redundancy, fire protection, and prevention of over-current levels and other abnormal operating conditions.

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